

K1J00020X

**PLUG-AND-SOCKET CONNECTOR LAYOUT**



**LEGENDS:**

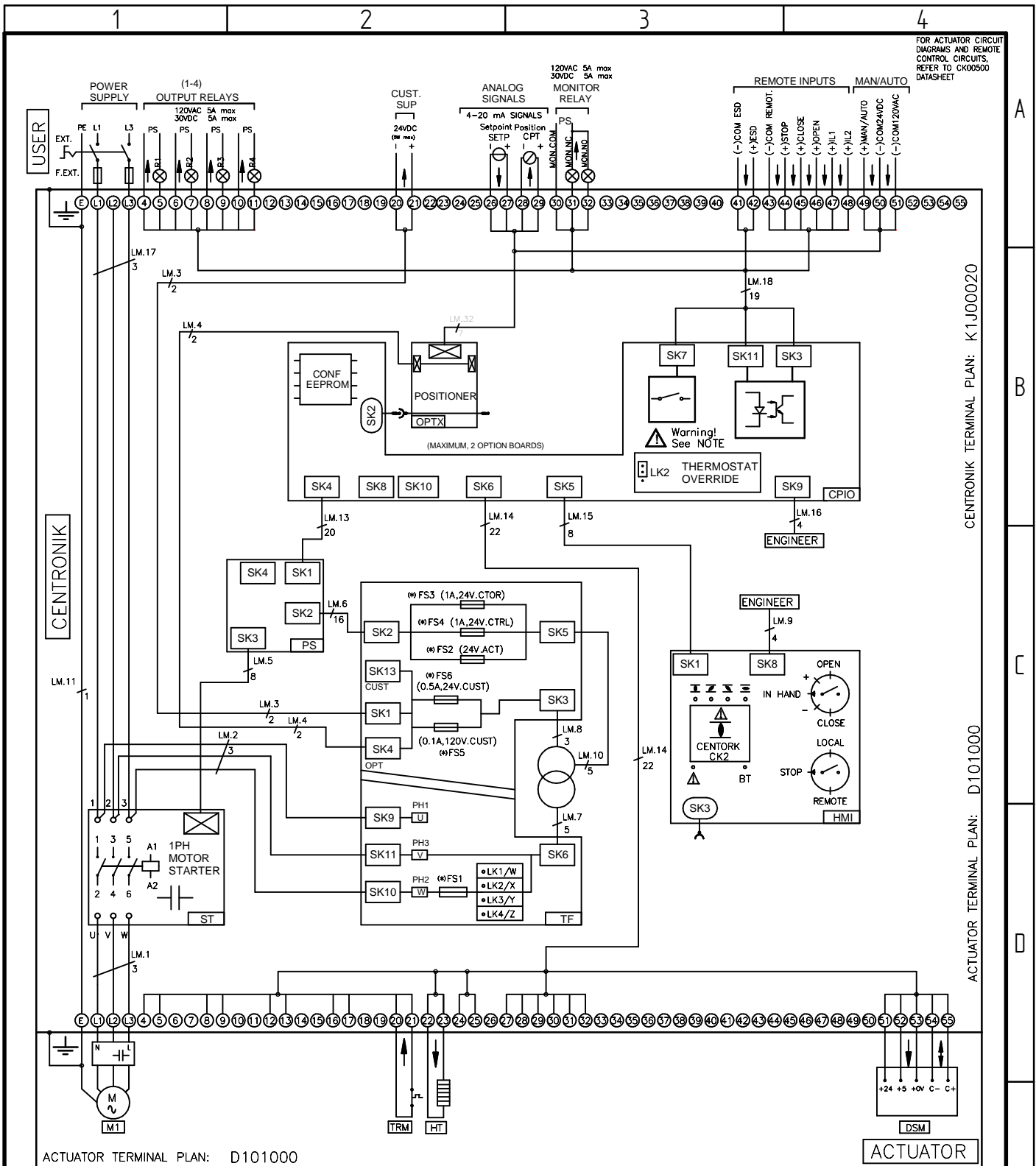
- M1** ELECTRIC MOTOR
- R1** RELAY OUTPUT No1 (SETTABLE)
- R2** RELAY OUTPUT No2 (SETTABLE)
- R3** RELAY OUTPUT No3 (SETTABLE)
- R4** RELAY OUTPUT No4 (SETTABLE)
- R5** RELAY OUTPUT No5 (SETTABLE)
- R6** RELAY OUTPUT No6 (SETTABLE)
- R7** RELAY OUTPUT No7 (SETTABLE)
- R8** RELAY OUTPUT No8 (SETTABLE)
- R9** RELAY OUTPUT No9 (SETTABLE)
- R10** RELAY OUTPUT No10 (SETTABLE)
- R11** RELAY OUTPUT No11 (SETTABLE)
- R12** RELAY OUTPUT No12 (SETTABLE)
- CS** CUSTOMER SUPPLY
- BS** BACKUP SUPPLY
- POSITIONER** POSITIONER IN/OUT ANALOG SIGNAL
- POSITIONER.LP** POSITIONER IN/OUT ANALOG SIGNAL. LOOP POWER
- MONIT.** MONITOR RELAY
- FIELDBUS** FIELDBUS CARD
- REMOTE** REMOTE INPUT CARDS
- ACTS** AUXILIARY CLOSE TORQUE SWITCH
- AOTS** AUXILIARY OPEN TORQUE SWITCH
- ACLS** AUXILIARY CLOSE LIMIT SWITCH
- AOLS** AUXILIARY OPEN LIMIT SWITCH
- IP1** VALVE MIDDLE TRAVEL POSITION SWITCH (No 1)
- IP2** VALVE MIDDLE TRAVEL POSITION SWITCH (No 2)
- IP3** VALVE MIDDLE TRAVEL POSITION SWITCH (No 3)
- IP4** VALVE MIDDLE TRAVEL POSITION SWITCH (No 4)
- CPT** CURRENT POSITION TRANSMITTER
- CTT** CURRENT TORQUE TRANSMITTER
- CPT.LP** CURRENT POSITION TRANSMITTER, LOOP POWER
- CTT.LP** CURRENT TORQUE TRANSMITTER, LOOP POWER
- CTS** CLOSE TORQUE SWITCH
- OTS** OPEN TORQUE SWITCH
- CLS** CLOSE LIMIT SWITCH
- OLS** OPEN LIMIT SWITCH
- TRM** THERMAL PROTECTION DEVICE (MOTOR WIND.)
- HT** ANTI-CONDENSATION HEATER
- BLK** BLINKER SWITCH
- POT** POTENTIOMETER (VALVE POSITION SIGNAL)
- CPT** CURRENT POSITION TRANSMITTER (VALVE POSITION SIGNAL)
- DSM** DIGITAL SWITCH MECHANISM (ELECTRONIC VALVE POSITION AND TORQUE SIGNALS)

**NOTES:**

1. THE TERMINAL PLAN SHOWS THE MULTI-TURN ELECTRIC ACTUATOR IN INTERMEDIATE POSITION, ACTUATOR CLOSES VALVE CLOCKWISE.
2. SEE ACTUATOR USER MANUAL AND DATASHEETS FOR TECHNICAL DATA, PARAMETERS AND DESCRIPTION OF THE ACTUATOR ELECTRIC AND ELECTRONIC EQUIPMENT.
3. IF THE ACTUATOR IS CONFIGURED TO BYPASS THE MOTOR PROTECTION THERMOSTAT (TRM), THE ACTUATOR WILL NO LONGER COMPLY WITH THE ESSENTIAL SAFETY REQUIREMENTS.
4. THE USER MUST FIT A CLASS 10 OVERLOAD RELAY. THE RELAY MUST BE SIZED ACCORDING TO THE OVERCURRENT PROT. DEVICE SETTING VALUE FOR THE MOTOR.
5. REFER TO THE MOTOR DATA SHEET FOR THIS VALUE. THE OVERLOAD RELAY MUST BE SIZED TO ENSURE THAT IT TRIPS WITHIN 10 SECONDS IN A FAULT CONDITION.
6. THE USER MUST COMPLETE A RISK ASSESSMENT AND IMPLEMENT WHATEVER MEASURES ARE REQUIRED TO ENSURE THAT THE RESULTANT SYSTEM COMPLIES WITH ALL APPLICABLE LEGISLATION.

PARAMETER	VALUE	DESCRIPTION
TYPE	K	MULTI-TURN ELECTRIC ACTUATOR, WITH CENTRONIK (DIGITAL SWITCH MECH.)
MAIN POWER SUPPLY	1	A.C. SINGLE PHASE
EXTRA CARD No 1	J	POSITIONER + CONTROL
EXTRA CARD No2	0	NO (WITHOUT)
MOTOR STARTER	0	REVERSIBLE CONTACTORS (STANDARD)
CUSTOMER SUPPLY & BLUETOOTH	0	24VDC±20% AT MAX.POW.OUTPUT 5W.
BACKUP SUPPLY & HEATER	2	NO BACKUP SUPPLY, HEATER INCLUDED
EXTRA SWITCH	0	STANDARD, WITHOUT

ISSUE		DATE		ISSUE		DATE			
1	FIRST RELEASE	25-10-17	3						
2			4						
SHEET 1/2	DATE	SIGN.	TERMINAL PLAN					FORMAT	DRAWING N°
MADE BY	25/10/2017	JB	WD CKC-CKRC CTK., DSM, 1PH, POSC, NOEX2, CTOR, CS24-IR, NOBK-HT, NOEXT					A4	K1J00020X - 1
CHECKED	25/10/2017	JP							
APPROVED	25/10/2017	JP							



ACTUATOR TERMINAL PLAN: D101000

ACTUATOR

**WARNING:** REFER TO SAFE USE AND INSTALLATION MANUAL OR CK00500 DATASHEET FOR APPROVED FUSES.

FS1: ACCORDING TO THE POWER SUPPLY VOLTAGE  
 110VAC/115VAC: FS1 (0,5 A)  
 ANY OTHER VOLTAGE: FS1 (0,25 A)

**TRANSFORMER TAPPING OPTIONS**

TAP	LV	PRIMARY TAP NOMINAL VOLTAGE (VAC 50/60Hz)	
		EU	HV
LK1	W	110/115/120	380
LK2	X	220/230	400
LK3	Y	240	415
LK4	Z	n/a	440

THE TERMINAL PLAN SHOWS THE MULTI-TURN ELECTRIC ACTUATOR IN INTERMEDIATE POSITION, ACTUATOR CLOSES VALVE CLOCKWISE.  
 REFER TO SAFE USE AND INSTALLATION MANUAL AND DATASHEETS FOR TECH. DATA, PARAMETERS AND DESCRIPTION OF THE ACTUATOR ELECTRIC AND ELECTRONIC EQUIPMENT.  
 ACTUATORS WITH SOLID STATE STARTER (SSS), THE ACTUATOR MUST BE PROTECTED USING SUITABLE RATED HIGH SPEED SEMI-CONDUCTOR FUSES ON THE INCOMING SUPPLY.  
 IF THE ACTUATOR IS CONFIGURED TO BYPASS THE MOTOR PROTECTION THERMOSTAT (TRM), THE ACTUATOR WILL NO LONGER COMPLY WITH THE ESSENTIAL SAFETY REQUIREMENTS.  
 THE USER MUST CONDUCT A RISK ASSESSMENT, AND IMPLEMENT WHATEVER EXTRA SAFETY MEASURES ARE REQUIRED, TO ENSURE THAT THE RESULTANT SYSTEM COMPLIES WITH THE LOW VOLTAGE DIRECTIVE, AND ANY OTHER LEGISLATION IN FORCE AT THE INSTALLATION SITE.

ISSUE	DATE	ISSUE	DATE
1	FIRST RELEASE	11-09-17	3
2			4

SHEET 2/2	DATE	SIGN.	WIRING DRAWING	This drawing and the information it contains are property of Rotork Controls Limited, and they will not be reproduced or disclosed, in whole or in part, without the prior written consent of Rotork.
MADE BY	25/10/2017	JB	WD CKC-CKRC CTK, DSM, 1PH, POSC, NOEX2, CTR, CS24-IR, NOBK-HT, NOEXT	
CHECKED	25/10/2017	JP		
APPROVED	25/10/2017	JP		

	FORMAT	DRAWING N°
	A4	K1J00020X-1